2.7Gbps Laser Driver with Modulation Compensation

**General Description**

The MAX3863 is designed for direct modulation of laser diodes at data rates up to 2.7Gbps. An automatic power-control (APC) loop is incorporated to maintain a constant average optical power. Modulation compensation is available to increase the modulation current in proportion to the bias current. The optical extinction ratio is then maintained over temperature and lifetime.

The laser driver can modulate laser diodes at amplitudes up to 80mA. Typical (20% to 80%) edge speeds are 50ps. The MAX3863 can supply a bias current up to 100mA. External resistors can set the laser output levels.

The MAX3863 includes adjustable pulse-width control to minimize laser pulse-width distortion. The device offers a failure monitor output to indicate when the APC loop is unable to maintain the average optical power.

The MAX3863 accepts differential CML clock and data input signals with on-chip 50Ω termination resistors. If a clock signal is available, an input data-retiming latch can be used to reject input pattern-dependent jitter. The laser driver is fabricated with Maxim’s in-house second-generation SiGe process.

**Features**

- Single +3.3V Power Supply
- 58mA Power-Supply Current
- Up to 2.7Gbps (NRZ) Operation
- On-Chip Termination Resistors
- Automatic Power Control (APC)
- Compensation for Constant Extinction Ratio
- Programmable Modulation Current Up to 80mA
- Programmable Bias Current Up to 100mA
- 50ps Typical Rise/Fall Time
- Pulse-Width Adjustment Circuit
- Selectable Data-Retiming Latch
- Failure Detector
- Mark-Density Monitor
- Current Monitors
- ESD Protection

**Applications**

- SONET and SDH Transmission Systems
- WDM Transmission Systems
- 3.2Gbps Data Communications
- Add/Drop Multiplexers
- Digital Cross-Connects
- Section Regenerators
- Long-Reach Optical Transmitters

**Ordering Information**

<table>
<thead>
<tr>
<th>PART</th>
<th>TEMP RANGE</th>
<th>PIN-PACKAGE</th>
</tr>
</thead>
<tbody>
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<td>MAX3863ETJ+</td>
<td>-40°C to +85°C</td>
<td>32 TQFN-EP*</td>
</tr>
<tr>
<td>MAX3863EGJ</td>
<td>-40°C to +85°C</td>
<td>32 QFN-EP*</td>
</tr>
</tbody>
</table>

*+Denotes a lead-free/RoHS-compliant package.
*EP = Exposed pad.

**Pin Configuration**

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim’s website at www.maxim-ic.com.
2.7Gbps Laser Driver with Modulation Compensation

ABSOLUTE MAXIMUM RATINGS

Supply Voltage $V_{CC}$ ...........................................-0.5V to +5.0V
DATA+, DATA- and CLK+, CLK- ...(VCC - 1.5V) to (VCC + 0.5V)
RTEN, EN, BIAS, MK+, MK-, PWC+, PWC-
MODMON, BIASMON, MODMON, MODCOMP,
APCFILT1, APCFILT2, BIASMAX, MODSET,
APCSET Voltage ...........................................-0.5V to (VCC + 0.5V)
MOD, MODN Voltage ..................................0 to (VCC + 1.5V)
MOD, MODN Current ..................................-20mA to +150mA
BIAS Current ...........................................-20mA to +150mA
MD Current ...........................................-5mA to +5mA
Operating Junction Temperature Range ..........-55°C to +150°C
Storage Temperature Range ......................-55°C to +150°C
Continuous Power Dissipation (TA = +85°C) ...1.3W
32-Pin QFN, TQFN (derate 21.2mW/°C above +85°C) ...1.3W
Processing Temperature (die) ....................+400°C
Lead Temperature (soldering, 10s) .................+300°C

Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

($V_{CC}$ = +3.15V to +3.6V, TA = -40°C to +85°C. Typical values are at $V_{CC}$ = +3.3V, IBIAS = 50mA, IMOD = 40mA, TA = +25°C, unless otherwise noted.) (Notes 1, 9)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>SYMBOL</th>
<th>CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power-Supply Current</td>
<td>ICC</td>
<td>(Note 2)</td>
<td>58</td>
<td>85</td>
<td>mA</td>
<td></td>
</tr>
<tr>
<td>Power-Supply Noise Rejection</td>
<td>PSNR</td>
<td>$f = 100$kHz, 100mVP-P (Note 10)</td>
<td>40</td>
<td></td>
<td>dB</td>
<td></td>
</tr>
<tr>
<td>Power-Supply Threshold</td>
<td></td>
<td>Output enabled</td>
<td>2.8</td>
<td></td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>Single-Ended Input Resistance</td>
<td></td>
<td>Input to VCC</td>
<td>40</td>
<td>50</td>
<td>60</td>
<td>Ω</td>
</tr>
<tr>
<td>Bias-Current Setting Range</td>
<td></td>
<td></td>
<td>4</td>
<td>100</td>
<td>mA</td>
<td></td>
</tr>
<tr>
<td>Bias-Current Setting Error</td>
<td></td>
<td>APC open loop, $I_{BIAS} = 100mA$, $T_{A} = +25°C$</td>
<td>-15</td>
<td></td>
<td>15</td>
<td>%</td>
</tr>
<tr>
<td></td>
<td></td>
<td>APC open loop, $I_{BIAS} = 4mA$, $T_{A} = +25°C$</td>
<td>-20</td>
<td></td>
<td>20</td>
<td>%</td>
</tr>
<tr>
<td>Bias Off-Current</td>
<td></td>
<td>EN high</td>
<td>0.1</td>
<td></td>
<td>mA</td>
<td></td>
</tr>
<tr>
<td>IBIAS to IBIASMON Ratio</td>
<td></td>
<td></td>
<td>34</td>
<td>40</td>
<td>46</td>
<td>mA/mA</td>
</tr>
<tr>
<td>Bias-Current Temperature Stability</td>
<td></td>
<td>APC open loop, $10mA \leq I_{BIAS} \leq 100mA$ (Note 3)</td>
<td>-480</td>
<td></td>
<td>480</td>
<td>ppm/°C</td>
</tr>
<tr>
<td></td>
<td></td>
<td>APC open loop, $4mA \leq I_{BIAS} \leq 100mA$ (Note 3)</td>
<td>±390</td>
<td></td>
<td></td>
<td></td>
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<tr>
<td>Modulation-Current Setting Range</td>
<td></td>
<td></td>
<td>7</td>
<td>80</td>
<td>mA</td>
<td></td>
</tr>
<tr>
<td>Modulation-Current Setting Error</td>
<td></td>
<td>APC open loop, 25Ω load, $T_{A} = +25°C$</td>
<td>-15</td>
<td></td>
<td>15</td>
<td>%</td>
</tr>
<tr>
<td>Modulation Off-Current</td>
<td></td>
<td>EN high</td>
<td>0.1</td>
<td></td>
<td>mA</td>
<td></td>
</tr>
<tr>
<td>Modulation-Current Temperature Stability</td>
<td></td>
<td>APC open loop (Note 3)</td>
<td>-480</td>
<td></td>
<td>480</td>
<td>ppm/°C</td>
</tr>
<tr>
<td>IMOD to IMODMON Ratio</td>
<td></td>
<td></td>
<td>38</td>
<td>46</td>
<td>53</td>
<td>mA/mA</td>
</tr>
<tr>
<td>Modulation Compensation Range</td>
<td>K</td>
<td>$K = \Delta I_{MODC}/\Delta I_{BIAS}$</td>
<td>0</td>
<td>1.5</td>
<td>mA/mA</td>
<td></td>
</tr>
<tr>
<td>MD Pin Voltage</td>
<td></td>
<td></td>
<td>1.75</td>
<td></td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>Monitor Photodiode Current Range</td>
<td>IMD</td>
<td></td>
<td>30</td>
<td>2000</td>
<td>µA</td>
<td></td>
</tr>
<tr>
<td>APC Loop Time Constant</td>
<td>tAPC</td>
<td>(Notes 3, 4)</td>
<td>1</td>
<td>4</td>
<td>1000</td>
<td>µs</td>
</tr>
<tr>
<td>APC Open Loop</td>
<td></td>
<td>$4mA \leq I_{BIAS} \leq 10mA$ (Note 3)</td>
<td>±390</td>
<td></td>
<td>mA</td>
<td></td>
</tr>
<tr>
<td>VMODMON to IMD Ratio</td>
<td>$R_{MODMON} = 4kΩ$</td>
<td>0.8</td>
<td>1.0</td>
<td>1.2</td>
<td>mV/µA</td>
<td></td>
</tr>
<tr>
<td>EN and RTEN Input High</td>
<td>$V_{IH}$</td>
<td></td>
<td>2.0</td>
<td></td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>EN and RTEN Input Low</td>
<td>$V_{IL}$</td>
<td></td>
<td>0.8</td>
<td></td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>FAIL Output High</td>
<td>$V_{OH}$</td>
<td>Source 150µA</td>
<td>2.4</td>
<td></td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>FAIL Output Low</td>
<td>$V_{OL}$</td>
<td>Sink 2mA</td>
<td>0.4</td>
<td></td>
<td>V</td>
<td></td>
</tr>
</tbody>
</table>
ELECTRICAL CHARACTERISTICS (continued)

(VCC = +3.15V to +3.6V, TA = -40°C to +85°C. Typical values are at VCC = +3.3V, IBIAS = 50mA, IMOD = 40mA, TA = +25°C, unless otherwise noted.) (Notes 1, 9)

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<tr>
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<th>CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single-Ended Input (DC-Coupled)</td>
<td>VIS</td>
<td>At high</td>
<td>VCC - 1.0</td>
<td>VCC - 0.1</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>At low</td>
<td>VCC + 0.05</td>
<td>VCC + 0.4</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>Single-Ended Input (AC-Coupled)</td>
<td>VIS</td>
<td>At high</td>
<td>VCC - 0.4</td>
<td>VCC - 0.05</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>At low</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Differential Input Swing</td>
<td>VID</td>
<td>DC-coupled</td>
<td>0.2</td>
<td>2.0</td>
<td>VP-P</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>AC-coupled</td>
<td>0.2</td>
<td>1.6</td>
<td>VP-P</td>
<td></td>
</tr>
<tr>
<td>Input Data Rate</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output Return Loss</td>
<td>R LIN</td>
<td>(Notes 3)</td>
<td>f ≤ 2.7GHz</td>
<td>17</td>
<td>dB</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>2.7GHz &lt; f ≤ 4GHz</td>
<td>14</td>
<td></td>
<td></td>
<td></td>
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<tr>
<td>Turn-Off Delay from EN</td>
<td></td>
<td>EN = high</td>
<td>1.0</td>
<td></td>
<td>µs</td>
<td></td>
</tr>
<tr>
<td>Setup Time</td>
<td>t SU</td>
<td>Figure 2</td>
<td>90</td>
<td></td>
<td>ps</td>
<td></td>
</tr>
<tr>
<td>Hold Time</td>
<td>t HD</td>
<td>Figure 2</td>
<td>90</td>
<td></td>
<td>ps</td>
<td></td>
</tr>
<tr>
<td>Pulse-Width Adjustment Range</td>
<td>ZL = 25Ω (Notes 3, 6)</td>
<td>±185</td>
<td>±220</td>
<td>ps</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Pulse-Width Stability</td>
<td>PWC+ and PWC- open (Notes 3, 6)</td>
<td>±18.5</td>
<td></td>
<td>ps</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Differential Pulse-Width Control Input Range</td>
<td>For PWC+ and PWC- (Notes 3, 7), VCM = 0.5V</td>
<td>-1.0</td>
<td>1.0</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Differential Mark Density</td>
<td>0% to 100%, VMK+ - VMK-</td>
<td>±0.85</td>
<td></td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Differential Mark-Density Voltage to Mark-Density Ratio</td>
<td>15.5</td>
<td></td>
<td>V%</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output Edge Speed</td>
<td>t R, t F</td>
<td>ZL = 25Ω (20% to 80%) (Notes 3, 6)</td>
<td>50</td>
<td>85</td>
<td>ps</td>
<td></td>
</tr>
<tr>
<td>Output Overshoot</td>
<td></td>
<td>ZL = 25Ω (Note 3)</td>
<td>±7</td>
<td></td>
<td>%</td>
<td></td>
</tr>
<tr>
<td>Random Jitter</td>
<td>δ</td>
<td>(Notes 3, 6)</td>
<td>0.8</td>
<td>1.3</td>
<td>ps RMS</td>
<td></td>
</tr>
<tr>
<td>Deterministic Jitter</td>
<td>Data Rate = 2.7Gbps (Notes 3, 8)</td>
<td>8</td>
<td>40</td>
<td>ps RMS</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Data Rate = 3.2Gbps (Notes 3, 8)</td>
<td>10</td>
<td>40</td>
<td>ps RMS</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Note 1: Specifications at -40°C are guaranteed by design and characterization.
Note 2: Excluding IBIAS, IMOD, IBIASMON, IMODMON, IFAIL, and IPWC. Input clock and data are AC-coupled.
Note 3: Guaranteed by design and characterization.
Note 4: An external capacitor at APCFILT1 and APCFILT2 is used to set the time constant.
Note 5: For both data inputs DATA+, DATA- and clock inputs CLK+, CLK-.
Note 6: Measured using a 2.7Gbps repeating 0000 0000 1111 1111 pattern.
Note 7: For pulse width, PW = 100%: Rp = Rn = 5000Ω (or open) or PWC+ = PWC- = +0.5V. For PW > 100%: Rp > Rn or PWC+ > PWC-. For PW < 100%: Rp < Rn or PWC+ < PWC-.
Note 8: Measured using a 2^13 - 1 PRBS with 80 zeros + 80 ones input data pattern or equivalent.
Note 9: AC characterization performed using the circuit in Figure 1.
Note 10: Power-Supply Noise Rejection (PSNR) = 20log10(VNOISE (on VCC)/ΔVOUT). VOUT is the voltage across the 25Ω load when no input is applied.
2.7Gbps Laser Driver with Modulation Compensation

Typical Operating Characteristics

($T_A = +25^\circ C$, unless otherwise noted. See Typical Operating Circuit.)

- **ELECTRICAL EYE DIAGRAM**
  
  - (IMOD = 80mA, DATA RATE = 2.7Gbps, PATTERN 213 - 1 + 80CID)
  
  - (IMOD = 80mA, DATA RATE = 3.2Gbps, PATTERN 213 - 1 + 80CID)
  
  - (IMOD = 7mA, DATA RATE = 2.7Gbps, PATTERN 213 - 1 + 80CID)

- **ELECTRICAL EYE DIAGRAM**
  
  - (IMOD = 7mA, DATA RATE = 3.2Gbps, PATTERN 213 - 1 + 80CID)

- **OPTICAL EYE DIAGRAM**
  
  - (IMOD = 40mA, DATA RATE = 2.5Gbps, PATTERN 213 - 1 + 80CID)
  
  - (IMOD = 40mA, DATA RATE = 3.2Gbps, PATTERN 213 - 1 + 80CID)

- **SUPPLY CURRENT (ICC) vs. TEMPERATURE**

  - (EXCLUDES BIAS AND MODULATION CURRENTS)

- **DETERMINISTIC JITTER vs. IMOD**

- **PULSE-WIDTH ADJUST vs. DIFFERENTIAL $V_{PW}$**
2.7Gbps Laser Driver with Modulation Compensation

Typical Operating Characteristics (continued)

(T_A = +25°C, unless otherwise noted. See Typical Operating Circuit.)

MODULATION CURRENT vs. MODULATION SET RESISTOR

MODULATION MONITOR VOLTAGE vs. MODULATION CURRENT

BIAS CURRENT vs. BIASMAX SET RESISTOR

BIAS MONITOR VOLTAGE vs. BIAS CURRENT

MONITOR DIODE CURRENT vs. APCSET RESISTOR

DIODE-CURRENT MONITOR VOLTAGE vs. MONITOR DIODE CURRENT

COMPENSATION (K) vs. RMODCOMP

POWER-SUPPLY NOISE REJECTION vs. FREQUENCY

SINGLE-ENDED S11 vs. FREQUENCY
# Pin Description

<table>
<thead>
<tr>
<th>PIN</th>
<th>NAME</th>
<th>FUNCTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>1, 4, 5, 8, 14, 19, 22, 27</td>
<td>VCC</td>
<td>Positive Supply Voltage</td>
</tr>
<tr>
<td>2</td>
<td>DATA+</td>
<td>Data Input, with On-Chip Termination</td>
</tr>
<tr>
<td>3</td>
<td>DATA-</td>
<td>Complementary Data Input, with On-Chip Termination</td>
</tr>
<tr>
<td>6</td>
<td>CLK+</td>
<td>Clock Input for Data Retiming, with On-Chip Termination</td>
</tr>
<tr>
<td>7</td>
<td>CLK-</td>
<td>Complementary Clock Input for Data Retiming, with On-Chip Termination</td>
</tr>
<tr>
<td>9</td>
<td>APCSET</td>
<td>Monitor Diode Current Set Point</td>
</tr>
<tr>
<td>10</td>
<td>APCFILT1</td>
<td>APC Loop Filter Capacitor. Short to ground to disable the correction loop through the monitor diode.</td>
</tr>
<tr>
<td>11</td>
<td>APCFILT2</td>
<td>APC Loop Filter Capacitor</td>
</tr>
<tr>
<td>12</td>
<td>PWC+</td>
<td>Input for Modulation Pulse-Width Adjustment. Connected to GND through RPWC.</td>
</tr>
<tr>
<td>13</td>
<td>PWC-</td>
<td>Complementary Input for Modulation Pulse-Width Adjustment. Connected to GND through RPWC.</td>
</tr>
<tr>
<td>15</td>
<td>MK+</td>
<td>Voltage Proportional to the Mark Density. MK+ = MK- for 50% duty cycle.</td>
</tr>
<tr>
<td>16</td>
<td>MK-</td>
<td>Voltage Inversely Proportional to the Mark Density</td>
</tr>
<tr>
<td>17</td>
<td>FAIL</td>
<td>Alarm for Shorts on Current Set Pins and APC Loop Failure Conditions, Active Low</td>
</tr>
<tr>
<td>18</td>
<td>BIAS</td>
<td>Laser Diode Bias Current Source (Sink Type) to Bias the Laser Diode. Connect to the laser with an inductor.</td>
</tr>
<tr>
<td>20</td>
<td>MOD</td>
<td>Driver Output. AC-coupled to the laser diode.</td>
</tr>
<tr>
<td>21</td>
<td>MODN</td>
<td>Complementary Driver Output. Connect to dummy load off-chip.</td>
</tr>
<tr>
<td>23</td>
<td>MD</td>
<td>Monitor Diode Connection</td>
</tr>
<tr>
<td>24</td>
<td>MDMON</td>
<td>Monitor for MD Current. Voltage developed across an external resistor from mirrored MD current.</td>
</tr>
<tr>
<td>25</td>
<td>MODMON</td>
<td>Monitor for Modulation Current. Voltage developed from IMOD mirrored through an external resistor.</td>
</tr>
<tr>
<td>26</td>
<td>BIASMON</td>
<td>Monitor for Bias Current. Voltage developed from IBIAS mirrored through an external resistor.</td>
</tr>
<tr>
<td>28</td>
<td>MODCOMP</td>
<td>Couples the Bias Current to the Modulation Current. Mirrors IBIAS through an external resistor. Open for zero coupling.</td>
</tr>
<tr>
<td>29</td>
<td>MODSET</td>
<td>External Resistor to Program IMODC (IMOD = IMODS + IMODC)</td>
</tr>
<tr>
<td>30</td>
<td>BIASMAX</td>
<td>External Resistor to Program the Maximum IBIAS</td>
</tr>
<tr>
<td>31</td>
<td>EN</td>
<td>Modulation and Bias Current Enable, Active Low. Current disabled when floating or high.</td>
</tr>
<tr>
<td>32</td>
<td>RTEN</td>
<td>Data Retiming Enable Input, Active Low. Retiming disabled when floating or high.</td>
</tr>
<tr>
<td>—</td>
<td>EP</td>
<td>Exposed Pad. The exposed pad must be soldered to circuit-board ground for proper thermal and electrical operation.</td>
</tr>
</tbody>
</table>
Detailed Description

The MAX3863 laser driver has two main components: a high-speed modulation driver and a biasing block with APC. The clock and data inputs to the modulation driver use CML logic levels. The optional clock signal synchronizes data transitions for minimum pattern-dependent jitter. Outputs to the laser diode consist of a switched modulation current and a steady bias current. The APC loop adjusts the laser diode bias current to maintain constant average optical power. Compensation of the modulation current can be programmed to keep a constant extinction ratio over time and temperature. The modulation output stage uses a programmable current source with a maximum current of 80mA. A high-speed differential pair switches the source to the laser diode. The rise and fall times are typically 50ps.

Optional Input Data Retiming

To eliminate pattern-dependent jitter in the input data, a synchronous differential clock signal should be connected to the CLK+ and CLK- inputs, and the RTEN control input should be connected low. The input data is retimed on the rising edge of CLK+. If RTEN is tied high or is left floating, the retiming function is disabled, and the input data is directly connected to the output stage. Leave CLK+ and CLK- open when retiming is disabled.

Mark-Density Outputs

The MK+ and MK- outputs monitor the input signal mark density. With a 50% mark density, both outputs are the same voltage. More ones cause the MK+ voltage to increase and the MK- voltage to decrease. Fewer ones than zeros cause MK- to be at a higher voltage than MK+.

Pulse-Width Control

A pulse-width adjustment range of 50% to 150% (±185ps) is available at 2.7Gbps. This feature compensates pulse-width distortion elsewhere in the system. Resistors at the PWC+ and PWC- pins program the pulse width. The sum of the resistors is 1kΩ. The pins can be left open for a 100% pulse width. A voltage also can control these pins. A differential voltage of 600mV (typ) gives ±185ps of pulse-width distortion.

Output Enable

The MAX3863 incorporates an input to enable current to the laser diode. When EN is low, the modulation and bias outputs at the MOD pin are enabled. When EN is high or floating, the output is disabled. In the disabled condition, bias and modulation currents are off.

Power-Supply Threshold

To prevent data errors caused by low supply, the MAX3863 disables the laser diode current for supply voltage less than 2.7V. The power-supply threshold and
the output-enable must be true to enable bias and modulation currents.

**APC Loop Enable**
The APC loop is enabled when an external capacitor is placed between the APCFILT1 and APCFILT2 pins. This capacitor sets the time constant of the APC loop. To open the APC loop, the APCFILT1 pin is shorted to ground. This shorts the feedback from the monitor diode and causes the bias current to rise to the maximum value set by the BIASMAX pin.

**APC Filter**
The APC loop keeps the average optical power from the laser constant. An external filter capacitor is used to stabilize the APC loop. The typical capacitor value is 0.01µF.

**APC Failure Monitor**
The MAX3863 provides an APC failure monitor (TTL/CMOS) to indicate an APC loop tracking failure. FAIL is set low when the APC loop cannot adjust the bias current to maintain the desired monitor current.

**Short-Circuit Protection**
The MAX3863 provides short-circuit protection for modulation, bias, and monitor current sources. If BIASMAX, MODSET, or APCSET is shorted to ground, the bias and modulation output are turned off and FAIL is active.

**Current Monitors**
The MAX3863 features monitor outputs for bias current (BIASMON), modulation current (MODMON), and monitor diode current (MDMON). The monitors are realized by mirroring a fraction of the current and developing a voltage across an external resistor. For the specified voltage to monitor diode current, use an external 4kΩ resistor at the MDMON output. Resistors for BIASMON and MODMON are 100Ω. The minimum voltage at the BIASMON and MODMON must be 2.1V for compliance.

\[ V_{BIASMON} = V_{CC} - \frac{I_{BIAS}}{40} \times 100Ω \]

\[ V_{MODMON} = V_{CC} - \frac{I_{MOD}}{45} \times 100Ω \]

\[ V_{MDMON} = \frac{I_{MD}}{4} \times 4kΩ \]

---

**Design Procedure**
When designing a laser transmitter, the optical output is usually expressed in terms of average power and extinction ratio. Table 1 shows relationships helpful in converting between the optical average power and the modulation current. These relationships are valid only if the mark density and duty cycle of the optical waveform are 50%.

For a desired laser average optical power (P_{AVG}) and optical extinction ratio (r_e), the required modulation current can be calculated based on the laser slope efficiency (\eta) using the equations in Table 1.

**Laser Current Compensation Requirements**
Determine static bias and modulation current requirements from the laser threshold current and slope efficiency. To use the APC loop with modulation compensation,
The laser driver automatically adjusts the bias to maintain the constant average power. The new bias condition requires proper compensation of the modulation current. The designer must predict the slope efficiency of the laser after its bias threshold current has changed.

The modulation and bias currents under a single operating condition:

For AC-coupled diodes:

\[
I_{\text{BIAS}} = I_{\text{TH}} + \frac{P_{\text{MOD}}}{2}
\]

The required compensation factor is then:

\[
K = \frac{I_{\text{MOD2}} - I_{\text{MOD1}}}{I_{\text{BIAS2}} - I_{\text{BIAS1}}}
\]

Once the value of the compensation factor is known, the fixed portion of the modulation current is calculated from:

\[
I_{\text{MODS}} = I_{\text{MOD}} - K \times I_{\text{BIAS}}
\]

**Current Limits**

To allow larger modulation current, the laser is AC-coupled to the MAX3863. In this configuration, a constant current is supplied from the inductor \(L_p\). When the MOD pin is conducting, half of \(I_{\text{MOD}}\) is supplied from \(L_p\) and half is from the laser diode. When MOD is off, the current from the inductor flows to the bias input. This reduces the current through the laser diode from the average of \(I_{\text{BIAS}}\) by half of \(I_{\text{MOD}}\). The resulting peak-to-peak current through the laser diode is then \(I_{\text{MOD}}\). See the Typical Operating Circuit. The requirement for compliance in the AC-coupled circuit:

- \(V_D\)—Diode bias point voltage (1.2V typ)
- \(R_L\)—Diode bias point resistance (5\(\Omega\) typ)
- \(L\)—Diode lead inductance (1nH typ)
- \(R_D\)—Series matching resistor (20\(\Omega\) typ)

\[
V_{\text{CC}} - \frac{I_{\text{MOD}}}{2} \times (R_D + R_L) \geq 1.8V
\]

The time constant associated with the output pullup inductor and the AC-coupling capacitor, impacts the pattern-dependent jitter. For this second-order network \(L_p\) usually limits the low-frequency cutoff. The capacitor \(C_D\) is selected so:

\[
C_D \times (R_D + R_L) > \frac{L_p}{(R_D + R_L)}
\]

Keep the peak voltage droopless than 3% of the peak-to-peak amplitude during the maximum CID period \(t\). The required time constant:

\[
2.8\% = 1 - e^{-\frac{1}{\tau}}
\]

\[
\tau = 35 \times t
\]

If \(\tau = L_p/25\Omega\), and \(t = 100UI = 40ns\), then \(L_p = 35\mu\text{H}\). Place a good high-frequency inductor of 2\muH on the transmission line to the laser. Then you can place a low-frequency inductor of 33\muH at a convenient distance from the driver output.

**Programming the Bias Current**

When the APC loop is enabled, the actual bias current is reduced from the maximum value to maintain constant current from the monitor diode. With closed-loop control, the bias current will be set by the transfer function of the monitor diode to laser diode current. For example, if the transfer function to the monitor diode is 10.0\(\mu\text{A/mA}\), then setting \(I_{\text{MON}}\) for 500\(\mu\text{A}\) results in \(I_{\text{BIAS}}\) equal to 50mA. The bias current must be limited in case the APC control is not used. The \(I_{\text{BIAS}}\) pin sets the maximum bias current. The \(I_{\text{BIAS}}\) current is established by an internal current regulator, which maintains the bandgap voltage of 1.2V across the external
2.7Gbps Laser Driver with Modulation Compensation

MAX3863

Figure 3. Functional Diagram

programming resistor. See the IBIASMAX vs. RBIASMAX graph in the Typical Operating Characteristics, and select the value of RBIASMAX that corresponds to the required current at +25°C.

\[ I_{\text{BIASMAX}} = 200 \times \frac{1.2V}{R_{\text{BIASMAX}}} \]

**Programming the Monitor Diode Current Set Point**

The APCSET pin controls the set point for the monitor diode current. An internal current regulator establishes the APCSET current in the same manner as the BIASMAX pin. See the IMD vs. RAPCSET graph in the Typical Operating Characteristics, and select the value of RAPCSET that corresponds to the required current at +25°C.

\[ I_{\text{MD}} = 5 \times \frac{1.2V}{R_{\text{APCSET}}} \]

**Programming the Modulation Current**

Two current sources combine to make up the modulation current of the MAX3863 as seen in Figure 3. A constant modulation current programmed at the MODSET pin and a current, proportional to IBIAS, that varies under control by the APC loop. See the Laser Current Compensation Requirements section for the desired values for IMODS and K. The portion of IMOD set by MODSET is established by an internal current regulator, which maintains the bandgap voltage of 1.2V across the external programming resistor. See the IMOD vs. RMODSET graph in the Typical Operating Characteristics and select the value of RMODSET that corresponds to the required current at +25°C. The current proportional to IBIAS is set by an external resistor at the MODCOMP pin. Open circuiting the MODCOMP pin can turn off the interaction between IBIAS and IMOD.
**Applications Information**

**Layout Considerations**

To minimize loss and crosstalk, keep connections between the MAX3863 output and the laser diode as short as possible. Use good high-frequency layout techniques and multilayer boards with uninterrupted ground plane to minimize EMI and crosstalk. Circuit boards should be made using low-loss dielectrics. Use controlled-impedance lines for the clock and data inputs, as well as the module output.

**Laser Safety and IEC 825**

Using the MAX3863 laser driver alone does not ensure that a transmitter design is compliant with IEC825. The entire transmitter circuit and component selections must be considered. Determine the level of fault tolerance required by each application and recognize that Maxim products are not designed or authorized for use as components in systems intended for surgical implant into the body, for applications intended to support or sustain life, or for any other application where the failure of a Maxim product could create a situation where personal injury or death may occur.

---

\[ I_{MOD} = I_{MODS} + K \times I_{BIAS} \]
\[ I_{MODS} = 200 \times \frac{1.2V}{R_{MODSET}} \]
\[ K = 200 \times \frac{5}{500+R_{MODCOMP}} \]

---

**Exposed Pad Package**

The exposed pad on the 32-pin QFN provides a very low thermal resistive path for heat removal from the IC. The pad is also electrical ground on the MAX3863 and must be soldered to the circuit board ground for proper thermal and electrical performance. Refer to Application Note 862: HFAN-08.1: Thermal Considerations of QFN and Other Exposed-Paddle Packages for additional information.
2.7Gbps Laser Driver with Modulation Compensation

Typical Operating Circuit

Chip Information
TRANSISTOR COUNT: 1786
PROCESS: Bipolar

Package Information
For the latest package outline information and land patterns, go to www.maxim-ic.com/packages.

<table>
<thead>
<tr>
<th>PACKAGE TYPE</th>
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<td>21-0140</td>
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<td>G3255-1</td>
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</table>
2.7Gbps Laser Driver with Modulation Compensation

Chip Topography

MAX3863

VCC BP34
DATA+ BP35
DATA- BP36
VCC BP37
VCC BP38
GND BP39
VCC BP40
VCC BP41
CLK+ BP42
CLK- BP43
VCC BP44
GND BP1
APCSET BP2
APCFLT1 BP3
APCFLT2 BP4
MK+ BP9
MK- BP10
GND BP7
VCC BP8
MK+ BP11
MK- BP12
BP13 BIAS
BP14 VCC
BP15 MOD
BP16 MOD
BP17 MODN
BP18 MODN
BP19 VCC
BP20 GND
BP21 MD
BP22 MDMON
BP23 GND
BP24 MODMON
BP25 GND
BP26 Vcc
BP27 GND
BP28 MODCOMP
BP29 MODSET
BP30 BIAS MAX
BP31 EN
BP32 RTC
BP33 GND
BP34 VCC
BP35 DATA+
BP36 DATA-
BP37 VCC
BP38 VCC
BP39 GND
BP40 VCC
BP41 VCC
BP42 CLK+
BP43 CLK-
BP44 VCC
81mil
81mil

MAXIM

13
## 2.7Gbps Laser Driver with Modulation Compensation

### Pad Coordinates

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<tr>
<th>NAME</th>
<th>PAD</th>
<th>COORDINATES (μM)</th>
<th>NAME</th>
<th>PAD</th>
<th>COORDINATES (μM)</th>
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Coordinates are for the center of the pad.
Coordinate 0, 0 is the lower left corner of the passivation opening for pad 1.
## 2.7Gbps Laser Driver with Modulation Compensation

### Revision History

<table>
<thead>
<tr>
<th>REVISION NUMBER</th>
<th>REVISION DATE</th>
<th>DESCRIPTION</th>
<th>PAGES CHANGED</th>
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<tr>
<td>0</td>
<td>1/02</td>
<td>Initial release.</td>
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<tr>
<td>1</td>
<td>10/02</td>
<td>Corrected bond pad 24 to MODMON in the Chip Topography.</td>
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<tr>
<td>2</td>
<td>5/03</td>
<td>Added the PKG CODE column to the Ordering Information table.</td>
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<td>Updated the package outline drawing in the Package Information section.</td>
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<tr>
<td>3</td>
<td>1/06</td>
<td>Added the TQFN package to the Ordering Information table and Absolute Maximum Ratings.</td>
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<td>Added the EP description to the Pin Description table.</td>
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<td>Changed the formulas in the Current Monitors section.</td>
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<td>Added the Exposed Pad Package section.</td>
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<td>Changed the RMDMON and RBIASMON values from 100Ω and 4kΩ to 4kΩ and 100Ω, respectively, in the Typical Operating Circuit.</td>
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<tr>
<td>4</td>
<td>11/08</td>
<td>Removed the dice package from the Ordering Information table and Chip Information section.</td>
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<td>Removed the package outline drawings and replaced with the table.</td>
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